

6.3 PARAMETRIC EQUATIONS AND MOTION

I. Definition

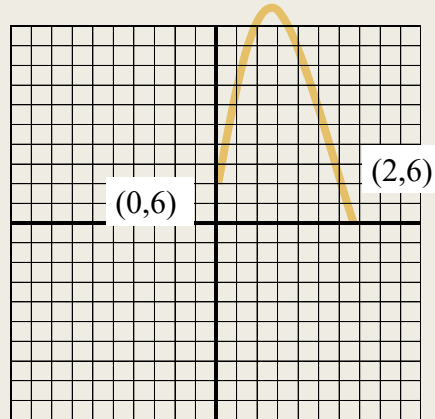
A.) Parametric Curve – Graph of ordered pairs (x, y) where $x = f(t)$ and $y = g(t)$.

B.) Parametric Equations– Any equation in the form of $x = f(t)$ and $y = g(t)$. t is called the parameter on an interval I .

Ex. 1– “Old School” – A ball is thrown in the air with an initial velocity of 32 ft./sec from a height of 6 ft. Write an equation to model the height of the ball as a function of time.

$$h(t) = -16t^2 + 32t + 6 \quad (1,22)$$

Let's look at the graph



If the ball is thrown directly upward, we can model the position of the ball using two different functions of t .

$$y = -16t^2 + 32t + 6 \quad x = 2$$

The horizontal position of the ball is now on a vertical axis, as it is in “real-life”. While the graph models its vertical position with respect to time, we can also see the velocity and the acceleration by changing our mode to parametric and our line to -0 (Tracer Mode in Y=)

II. Graphing by Hand

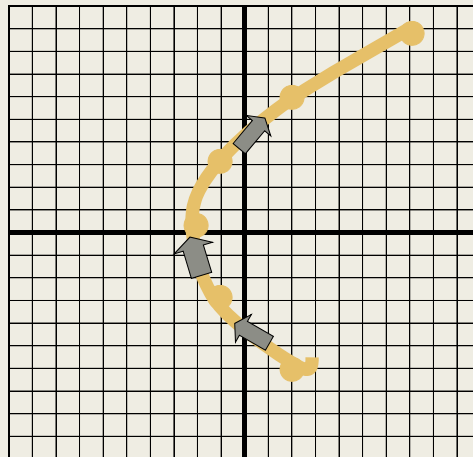
Ex. 2- Graph the following parametric equation by hand.

$$x = t^2 - 2$$

$$y = 3t \quad \text{for } -2 \leq t \leq 3$$

Make a table:

t	x	y
-2	2	-6
-1	-1	-3
0	-2	0
1	-1	3
2	2	6
3	7	9



III. Eliminating the Parameter

A.) Ex. 3- Determine the graph to the parametric equation by eliminating the parameter.

$$x = 2t + 3$$

$$y = t^2 \quad \text{for } -3 \leq t \leq 3$$

$$\begin{aligned} x &= 2t + 3 & y &= \left(\frac{x-3}{2}\right)^2 \\ t &= \frac{x-3}{2} & y &= \frac{1}{4}x^2 - \frac{3}{2}x + \frac{9}{4} \quad -3 \leq x \leq 9 \end{aligned}$$

B.) Ex. 4- Determine the graph to the parametric equation by eliminating the parameter.

$$x = \cos t \quad y = \sin t$$

$$t = \cos^{-1} x$$

$$y = \sin(\cos^{-1} x) \leftarrow \text{Very unfamiliar and hard to work with!}$$

What if we squared both sides of both equations?

$$x^2 = \cos^2 t$$

$$y^2 = \sin^2 t$$

Now, add the equations!

$$x^2 + y^2 = \cos^2 t + \sin^2 t$$

$$x^2 + y^2 = 1 \leftarrow \text{The circle centered at the origin with a radius of 1}$$

IV. Lines and Line Segments

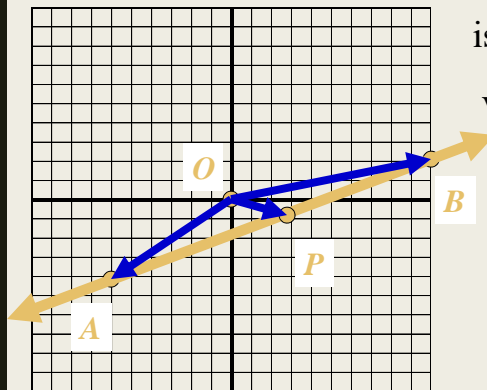
A.) Ex. 5- Find the parameterization for the line through the points $(-3, -3)$ and $(5, 1)$.

Let $P(x, y)$ be a point on the line through A and B and let O be the origin.

The vector $\vec{OP} - \vec{OA} = \vec{AP}$

is a scalar multiple of the

vector $\vec{OB} - \vec{OA} = \vec{AB}$



$$\overrightarrow{OP} = \langle x, y \rangle \quad \overrightarrow{OA} = \langle -3, -3 \rangle \quad \overrightarrow{OB} = \langle 5, 1 \rangle$$

$$\overrightarrow{OP} - \overrightarrow{OA} = t(\overrightarrow{OB} - \overrightarrow{OA})$$

$$\langle x+3, y+3 \rangle = t\langle 8, 4 \rangle$$

$$x+3 = 8t \quad y+3 = 4t$$

$$x = 8t - 3 \quad y = 4t - 3$$

$$-\infty < t < \infty$$

Ex. 6 - Find the parameterization for the line through the points $A=(3, 4)$ and $B=(6, -3)$.

$$\overrightarrow{OP} = \langle x, y \rangle \quad \overrightarrow{OA} = \langle 3, 4 \rangle \quad \overrightarrow{OB} = \langle 6, -3 \rangle$$

$$\overrightarrow{OP} - \overrightarrow{OA} = t(\overrightarrow{OB} - \overrightarrow{OA})$$

$$\langle x-3, y-4 \rangle = t\langle 3, -7 \rangle$$

$$x-3 = 3t \quad y-4 = -7t$$

$$x = 3t + 3 \quad y = -7t + 4 \quad -\infty < t < \infty$$

What if we wanted the line segment with endpoints A and B ?

Which values of t produce these endpoints?

$$\begin{array}{l} 3t + 3 = 3 \quad 3t + 3 = 6 \\ t = 0 \quad t = 1 \quad 0 \leq t \leq 1 \end{array}$$

V. Simulating Motion

Ex. 7-A particle moves along a horizontal line so that the position s (in feet) at any time $t \geq 0$ seconds is given by the function $s(t) = t^3 - 8t + 1$. Estimate the values at which the particle changes direction given $-3 \leq t \leq 3$.

1. Graph it. Place the equation in X_{1T} and choose an arbitrary Y_{1T} value.

$$X_{1T} = T^3 - 8T + 1$$

$$Y_{1T} = 4$$

2. What kind of window do we need?

$$T : [-3, 3] \quad X : [-10, 50] \quad Y : [0, 6]$$

3. Trace it.

$$t = \pm 1.637$$

Another way: Let $Y_{1T} = T$. $X_{1T} = T^3 - 8T + 1$

$$Y_{1T} = T$$

Window:

$$T : [-3, 3] \quad X : [-10, 50] \quad Y : [-10, 10]$$

Now we can visually see when the particle changes direction!

VI. Projectile Motion

A.) Not everything is straight vertically or horizontally. Take for example, hitting a baseball. There is both a horizontal and vertical component. The **velocity vector** is

$$\mathbf{v} = \langle v_0 \cos \theta, v_0 \sin \theta \rangle$$

The path that the object takes can be modeled by the parametric equations

$$x = (v_0 \cos \theta)t$$

Horizontal Distance

$$y = -16t^2 + (v_0 \sin \theta)t + y_0$$

Vertical Position

B.) Ex. 8- Sally hits a softball 2.5 feet above the plate with an initial speed of 110 feet per second at an angle of 22° with the horizontal. Will the ball clear the 5 ft. fence 250 feet away?

First, determine the equations for the ball:

$$X_{T_1} = (110 \cos 22^\circ)t$$

$$Y_{T_1} = -16t^2 + (110 \sin 22^\circ)t + 2.5$$

Now, determine the window

$$T : [0, 5] - T_{\text{step}} : .1 \quad X : [0, 280] \quad Y : [0, 30]$$

Now, graph and trace to see if it clears the wall

C.) Determine the equations for the wall:

$$X_{T_2} = 250$$

$$Y_{T_2} = 5$$

Change your MODE to Simultaneous

Now, just graph to see if it clears the wall

D.) General the equation for the wall:

$$X_{T_2} = \text{Distance}$$

$$Y_{T_2} = \frac{(\text{Wall's height}) \times T}{T_{\max}}$$

VII. Modeling Ferris Wheels

Ex. 9 - A Ferris wheel with a radius of 20 feet makes 1 complete revolution every 10 seconds. The lowest point of the Ferris wheel is 5 feet above the ground. Determine the parametric equations which will model the height of a rider starting in the 3 o'clock position at $t = 0$.

- Center the Ferris wheel on the vertical axis such that the center will be at the point $(0, 25)$.

$$x = 20 \cos \theta$$

- We know, from Chapter 5 that

$$y = 25 + 20 \sin \theta$$

- But, θ must be in terms of t . Since it takes 10 sec. to complete 1 revolution,

$$\frac{360^\circ}{10 \text{ sec}} = \frac{36^\circ}{1 \text{ sec}}$$

- Therefore,

$$\theta = 36T$$

and

$$\begin{pmatrix} X_{T_1} = 20 \cos(36t) \\ Y_{T_1} = 25 + 20 \sin(36t) \end{pmatrix}$$